

Intelligent Agents And Distributed Models For Cooperative Task Support



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Introduction



- ⌘ EPSRC / National Grid project done by Rak
- ⌘ Began as investigation of interface issues – identified hole in current research – on-line support cooperative tasks
- ⌘ work involves operations research, task modelling and intelligent agents
- ⌘ applied to control room - though more generic

Operations Research



- ⌘ Analysing work environments to effect changes to or to support work practices
- ⌘ This work: Decision Support Systems
- ⌘ Recent work: using Artificial Intelligence
 - ☑ may not be useful for on-line systems
 - ☑ can incur high development costs
- ⌘ Computer Supported Cooperative work
 - ☑ growing field; seemed appropriate here

Application for Work



⌘ National Grid Control Room

- ☑ Engineers control flow of electricity across the country, cope with outages, maintenance

⌘ (Real) Example Switching Scenarios

- ☑ 10 outage and substation rearrangements

⌘ Transmission Despatch Team

- ☑ various engineers to perform tasks at appropriate times in correct sequence.

⌘ Aim: provide system to speed up such tasks

The Agent Approach



- ⌘ Agents : autonomous entities, interacting with environment and others, flexible.
- ⌘ Generic agent model used
 - ☑ easier to scale system/tailor to environment
- ⌘ So separate agent from domain knowledge
- ⌘ System produced provides indirect management actions by agents to aid users
 - ☑ ensures user sees what is relevant

The Task Model



- ⌘ Approach – analyse tasks and distribute knowledge as local task automata
 - ☑ Such state-based approach natural way of representing sequences of task activity
- ⌘ Token passing to schedule task segments
 - ☑ many tasks supported at once
- ⌘ Planned support actions embedded
 - ☑ connected agents process such instructions, deliver task support actions to human users

Interface Agents



⌘ Interface agents - influence user behaviour

- ☑ control information presented to user

- ☑ control input permissions for different screens so only active tasks seen by user

- ☑ by co-ordinating actions across all involved users, the group of users is synchronised

⌘ Indirect management system

- ☑ supports users without adding to workload

BDI Model of Agent



⌘ Beliefs of agent

- ☑ models of / connections to work environment
- ☑ substation settings, in the example

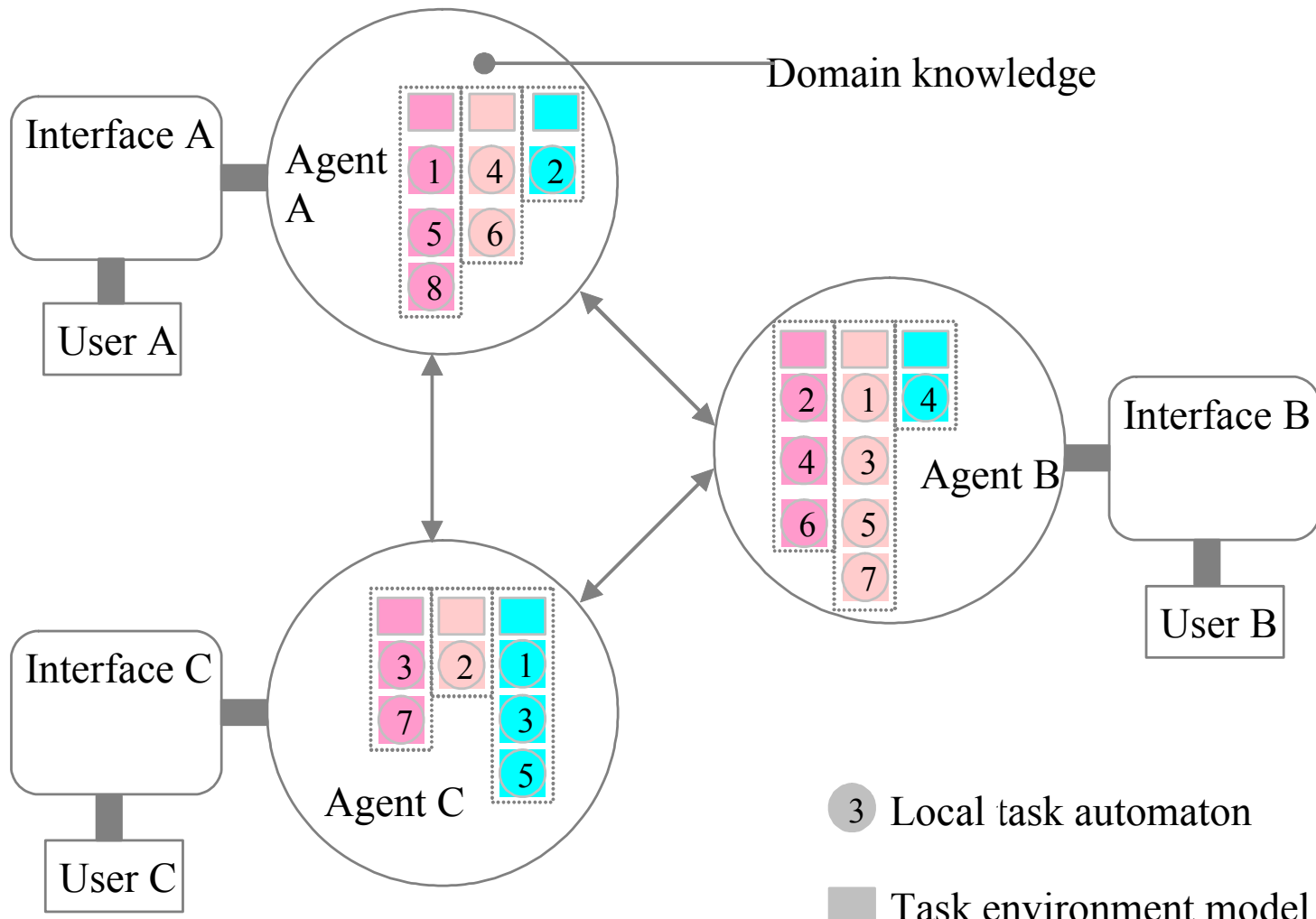
⌘ Desires

- ☑ process active automata to final state
- ☑ (ie to finish the task)

⌘ Intentions

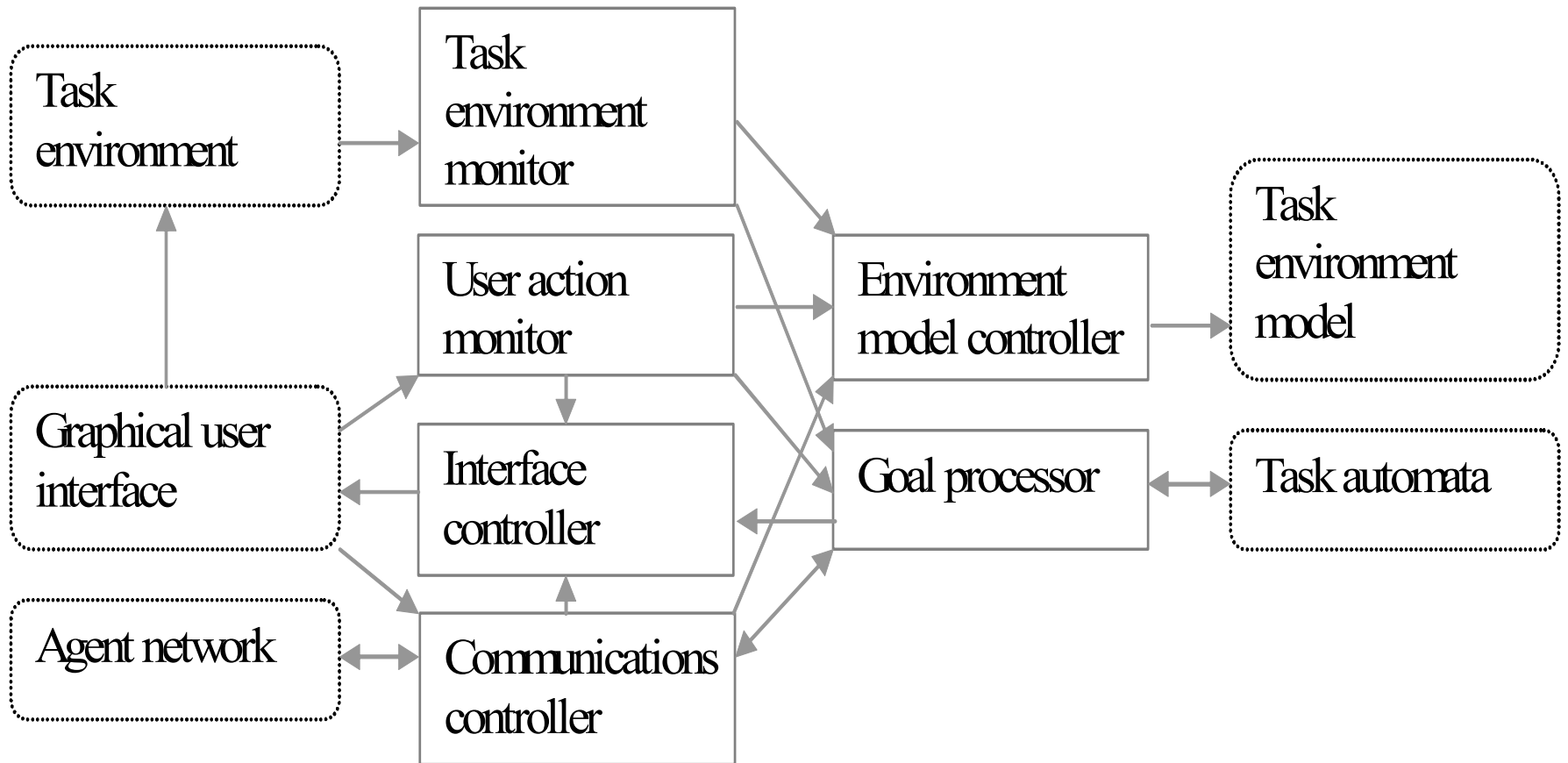
- ☑ represented by support actions in local task automata

Example Agent Model (3 user/task)



Each user works via single interface controlled by agent; all agents interface with each other

The Generic Agent Model



Interface

Agent Processor Modules

Models

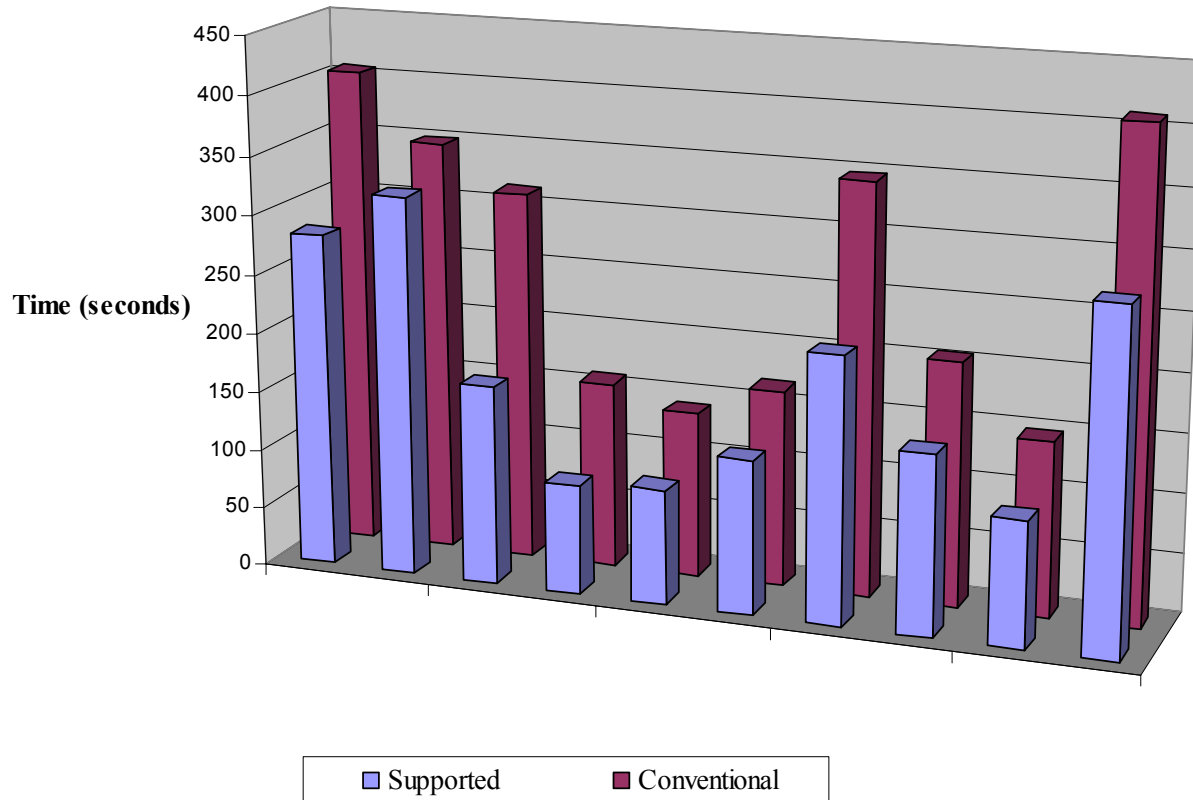
Testing of System



- ⌘ 10 tasks presented to volunteer teams
- ⌘ Completion times measured for supported and unsupported test runs
- ⌘ Run for all tasks in *pre-planned* order
- ⌘ And *ad-hoc*, where task order up to user (except for safety aspects)
 - ☑ the latter tests flexibility of system when dealing with random nature of ad-hoc cooperative environments

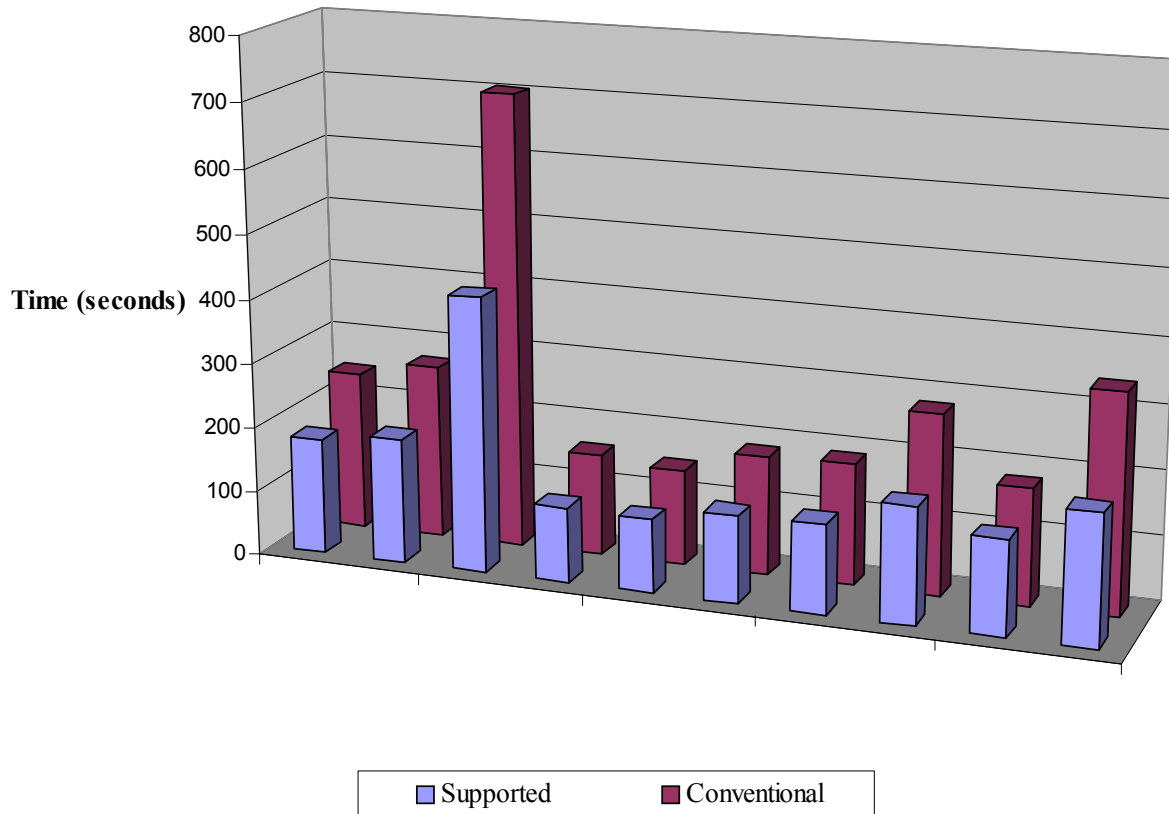
Effects On Task Times – Ad-Hoc

Individual task performance (ad-hoc process schedule)



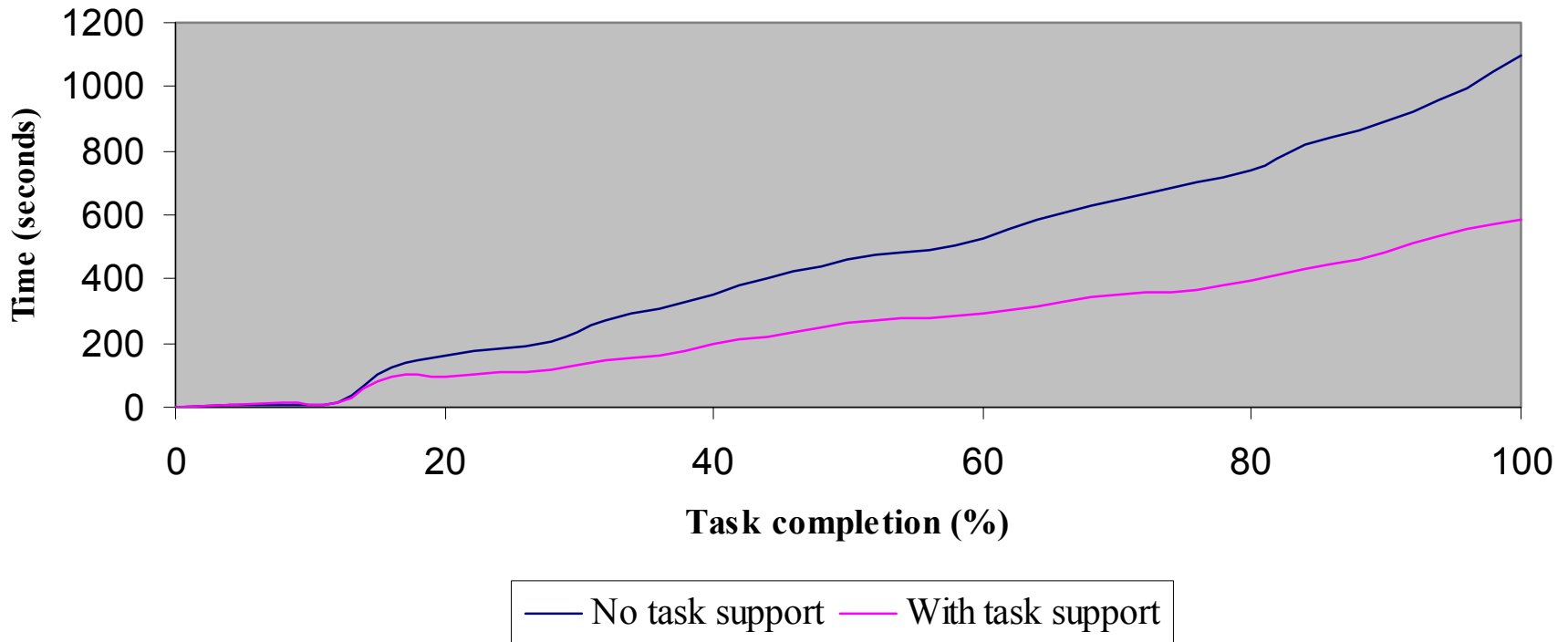
Effects on Times - Pre-Planned

Individual task performance (pre-planned process schedule)



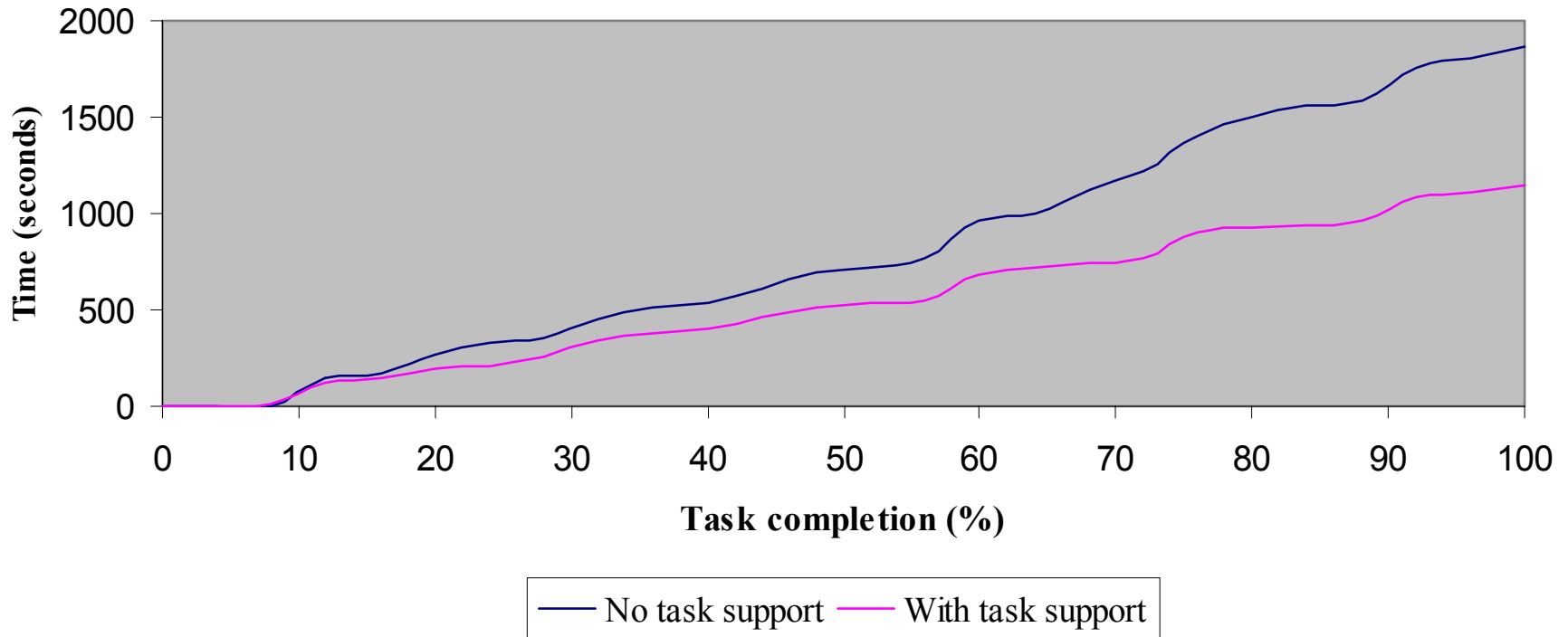
Average Times Taken - Ad-Hoc

Group performance (Ad-hoc process schedule)



Average Times – Pre-Planned

Group performance (Pre-planned process schedule)



Conclusion



- ⌘ Various methods applied to cooperative supported work
 - ☑ enhanced automata structure for distributed task model
 - ☑ plus flexible interface agent community
- ⌘ Solution successfully reduces time taken for completion of cooperative tasks

Thanks to EPSRC and National Grid