

OBTAINING MAXIMUM FEEDBACK AND DESIRED PHASE MARGIN

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Overview

- ◆ **Bode's fundamental work uses asymptotes to allow a system to be stabilised having suitable gain and phase margin, and max possible gain over a given bandwidth**
(It's a method of placing poles/zeros)
- ◆ **But if specify too high a bandwidth, for instance, actual phase margin far too low**
- ◆ **A solution is presented, which is consistent with Bode's aims**



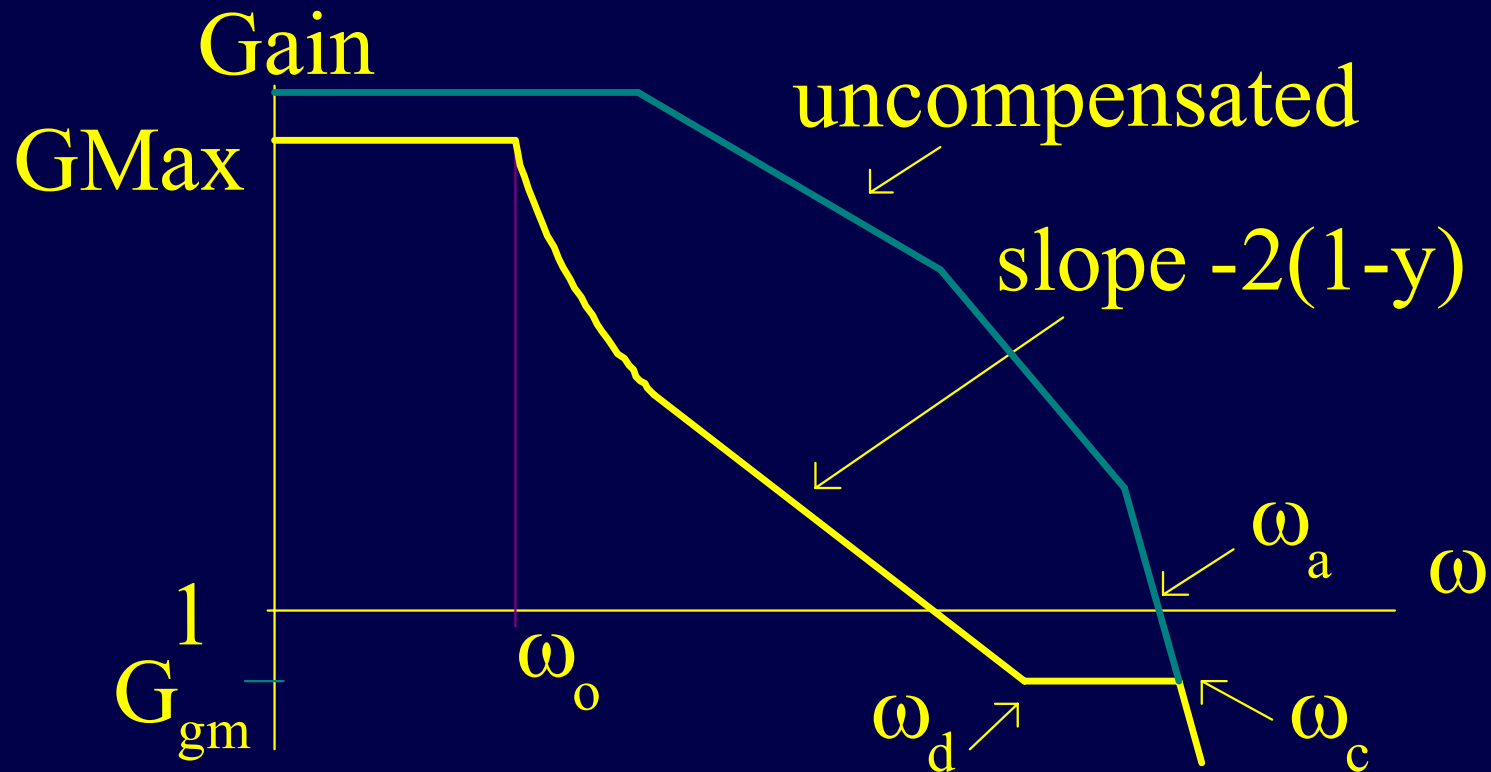
Specification

- ◆ Uncompensated system
 - ◆ Gain = 1 at ω_a then its order is n
 - ◆ As Phase = $-n*\pi/2$, unstable if $n>2$
- ◆ Compensated system specified to have
 - ◆ Phase margin, PM
 - ◆ Gain margin, GM
 - ◆ Max possible gain up to ω_o (bandwidth)
- ◆ Define $y = PM/\pi$; $x = GM$, then

$$G_{Max} = 40(1-y) \log_{10} \left(\frac{4(1-y)}{n} 10^{x/20n} \frac{\omega_a}{\omega_o} \right) - x$$



Frequency Shape to achieve this



Slope $-2(1-y) \rightarrow \text{Phase} = -\pi + \text{PM};$

'Bode Step' $\omega_d \dots \omega_c$: cancel phase due to $-n$ slope



Loop Transfer Function

$$\frac{G_{\text{Max}}}{T^2 s^2 + Ts + 1} \frac{1 + s/\omega_1}{1 + s/\omega_2} \frac{(1 + s/\omega_d)^2}{(1 + s/\omega_c)^n}, \text{ where } T = \frac{1}{\omega_0}$$

Second order element for low freq response.

(easier for students to understand than Bode's irrational element)

Lead Lag to approximate slope $-2(1-y)$

Can be better to have multiple lead lags



Problem

Slope $-2(1-y)$ from ω_d/m to ω_d where

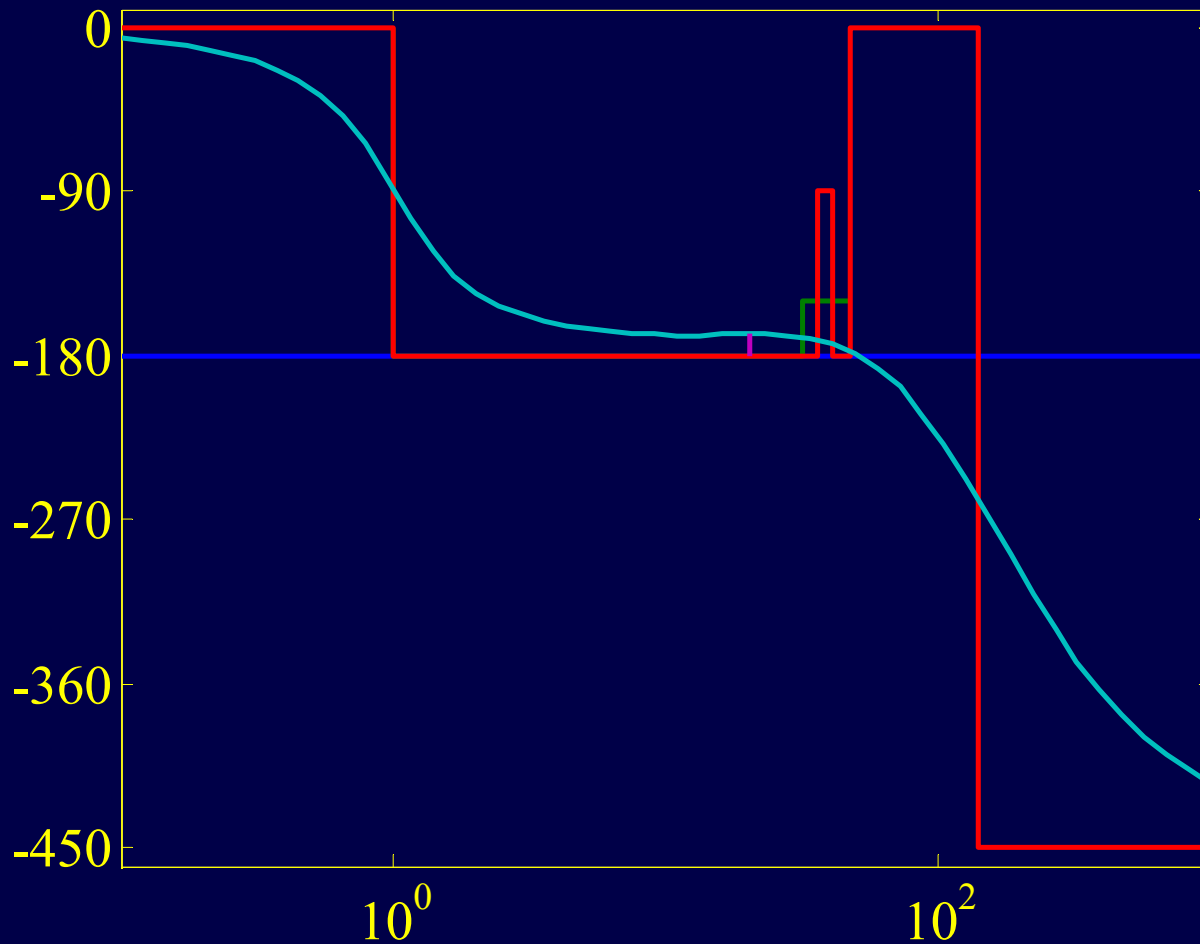
$$m = 2^{1-\frac{1}{y}} \frac{\omega_d}{\omega_o} \quad \text{PM} = \begin{matrix} 30^\circ & 45^\circ \\ 2^{1-\frac{1}{y}} = 0.03 & 0.125 \end{matrix}$$

For $\text{PM}=30^\circ$, ω_d must be at least 30 times ω_o and preferably much larger.

That is if bandwidth ω_o too large, there wont be region where slope $-2(1-y)$ and phase not $-\pi+\text{PM}$



For instance – Phase response



ω_o 1rad/s

GM 15dB

PM 30°

ω_a 100 rad/s

n 5

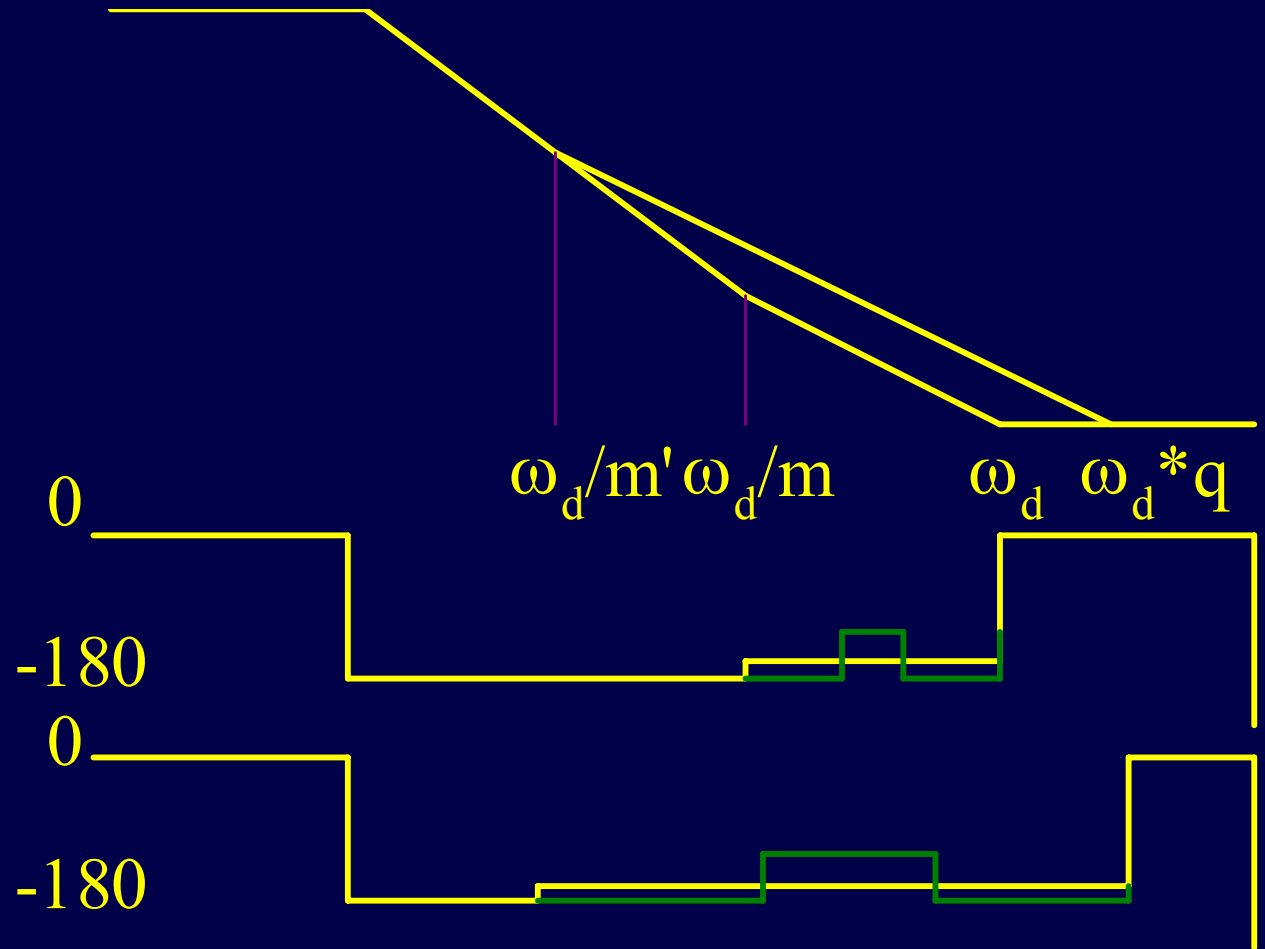
PM actual

11.6°

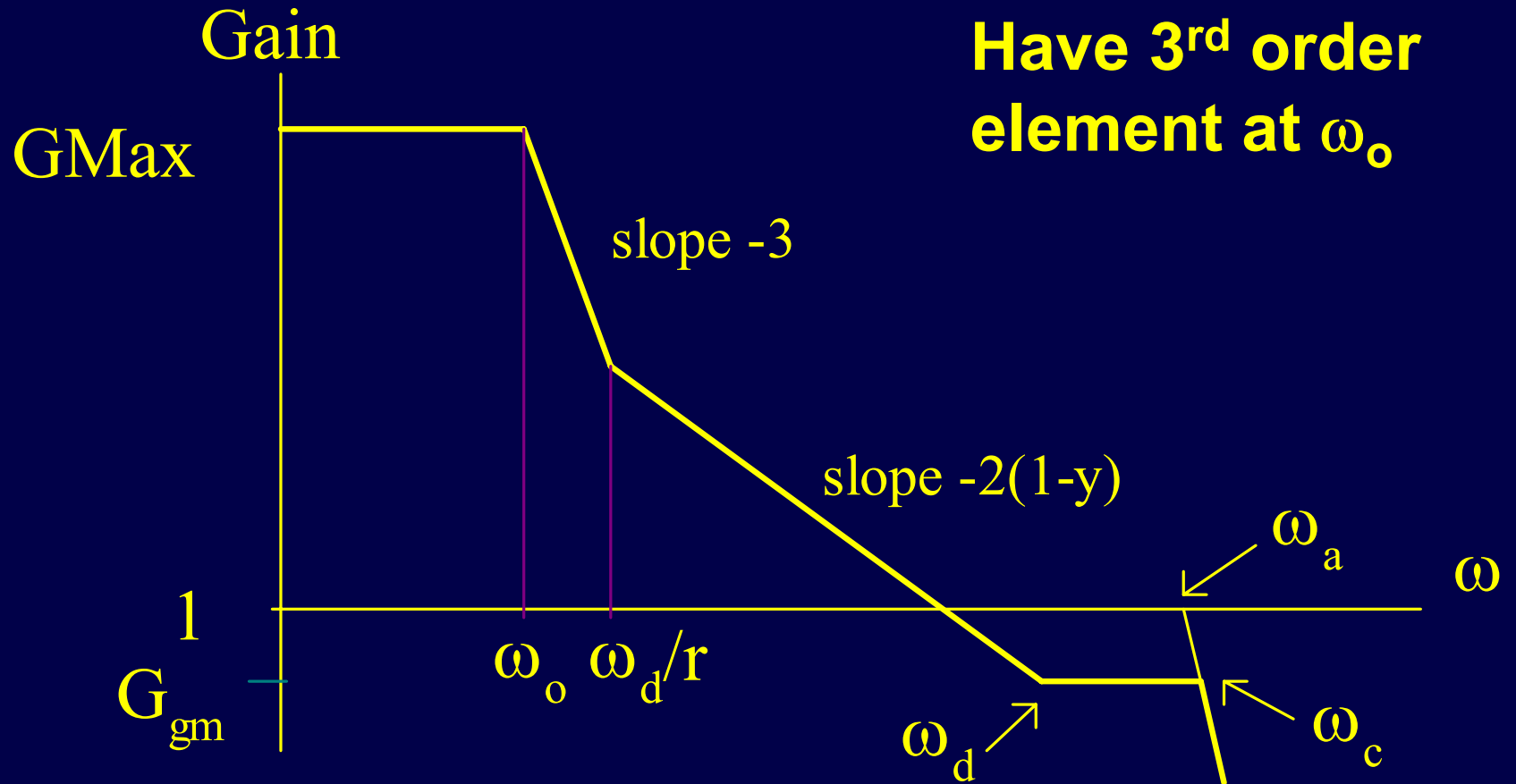


Means of extending $-2(1-y)$

a) reduce
Bode Step
not good.
ignores
Bode's
stability
analysis



Better – extend $-2(1-y)$ to low freq



Now 'length' of $-2(1-y)$ given by

$$r = 2 \frac{2(y-1)}{1+2y} \frac{\omega_d}{\omega_0} \quad \text{PM} = \quad 30^\circ \quad 45^\circ$$
$$2 \frac{2(y-1)}{1+2y} = 0.42 \quad 0.5$$

For same system as shown earlier

PM actual was 11.6° , with fix PM actual 27.5°

IF GM reduced from 15dB to 10dB

PM actual 9.8° or with fix PM actual 23.1°

Can achieve $\text{PM}=30^\circ$ if specify higher PM



Conclusion

- ◆ Analysis has shown why a design using Bode's method may not have the desired phase margin, particularly when seeking too high a bandwidth. For such situations, however, a simple successful solution to the problem is provided.

Acknowledgement

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