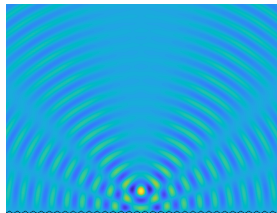
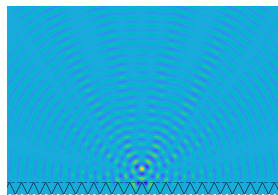


Integral equations and boundary element methods for rough surface scattering (RSS)



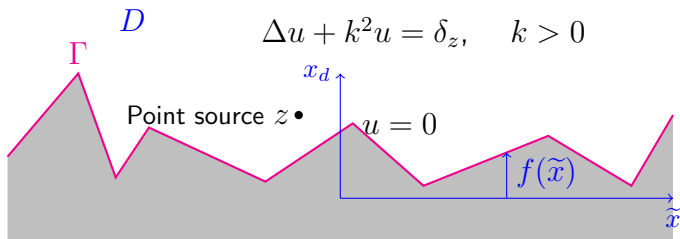
Simon Chandler-Wilde

Department of Mathematics
and Statistics
University of Reading, UK

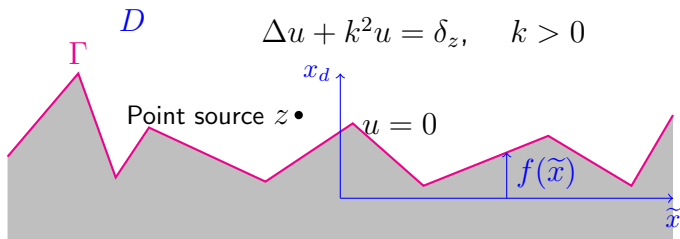


With: Martin Averseng & Euan Spence (Bath, UK)

INI Computational Methods for Multiple Scattering Workshop, April 2023

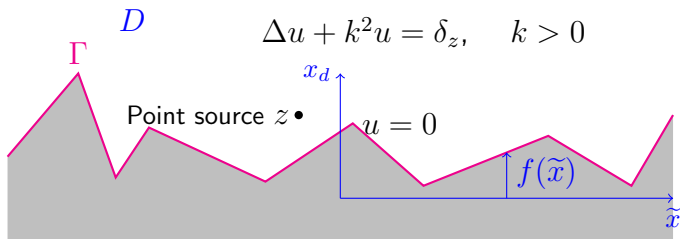


Many interesting **computational and numerical analysis** challenges!



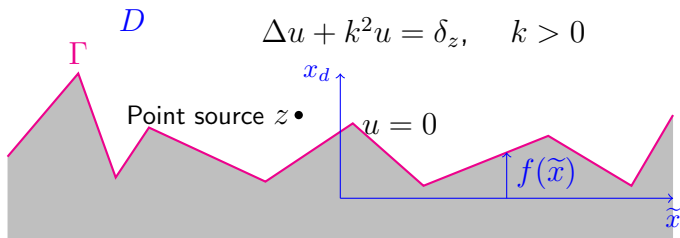
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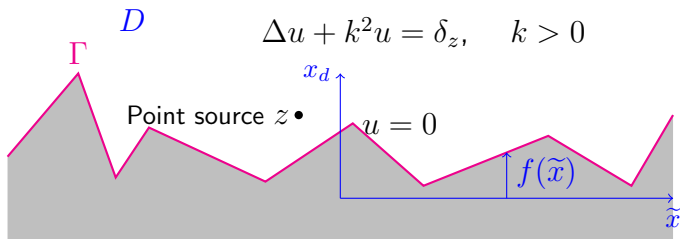
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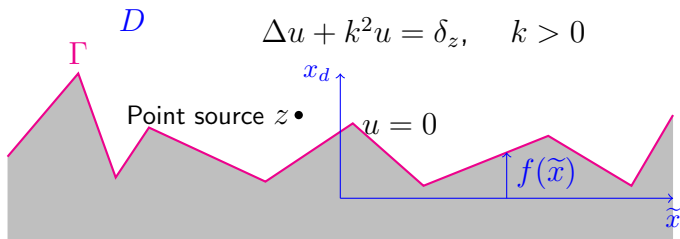
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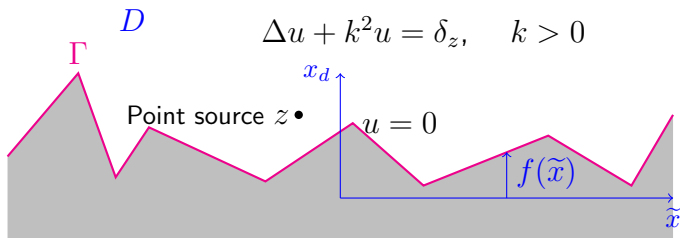
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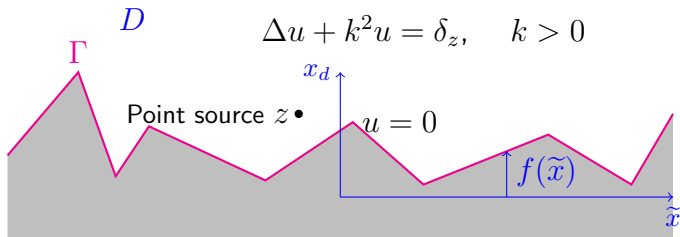
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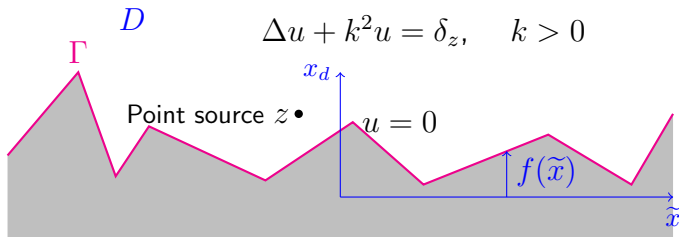
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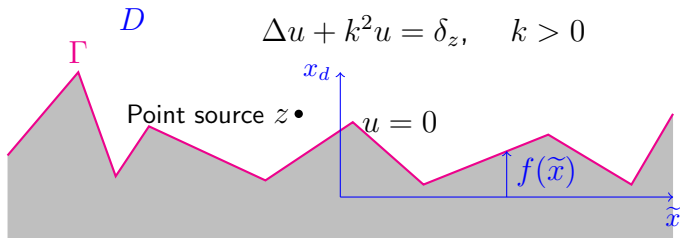
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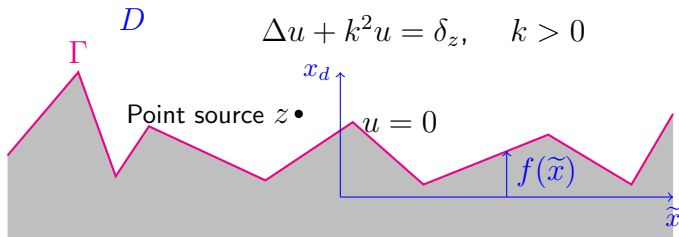
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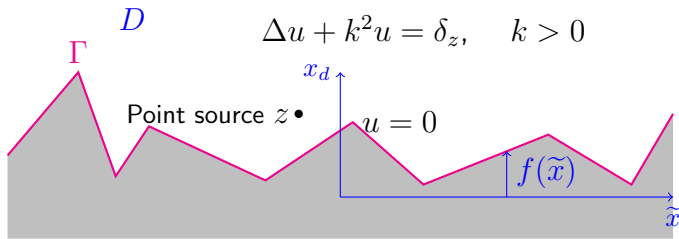
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Tools for convergence of Galerkin methods and GMRES

Suppose that H is a complex Hilbert space with norm $\|u\| = \sqrt{(u, u)}$, e.g.

$$H = L^2(\Gamma), \quad (u, v) = \int_{\Gamma} u \bar{v} \, ds, \quad \|u\|^2 = \int_{\Gamma} |u|^2 \, ds.$$

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Céa's Lemma. Let $H_N \subset H$ be a closed subspace. Then, $\forall g \in H$, \exists a unique *Galerkin approximation* $u_N \in H_N$ to $u := A^{-1}g$, defined by

$$(Au_N, v_N) = (g, v_N), \quad \forall v_N \in H_N,$$

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$$\|u - u_N\| \leq \frac{\|A\|}{\gamma} \inf_{v_N \in H_N} \|u - v_N\|.$$

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Theorem (corollary of field of values estimate in Beckermann et al. 2006). Let r_m be the residual after m steps of GMRES applied to (X). Then

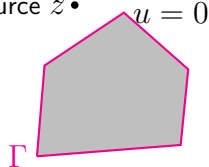
$$\frac{\|r_m\|_2}{\|r_0\|_2} \leq \varepsilon \quad \text{provided} \quad m \geq \frac{3\sqrt{3}}{4} \frac{\|A\|}{\gamma} \text{cond}(M) \log\left(\frac{8}{\varepsilon}\right),$$

where $M = [(\varphi_n, \varphi_m)]$ is the mass matrix.

Integral equation methods: bounded obstacle case

Point source $z \bullet$

D

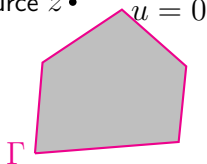


$$\Delta u + k^2 u = \delta_z, \quad k > 0$$

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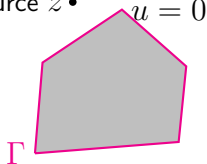
By Green's theorem, where $\Phi(x, y) := \frac{e^{ik|x-y|}}{4\pi|x-y|}$ and $u^i(x) := \Phi(x, z)$,

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Point source $z \bullet$

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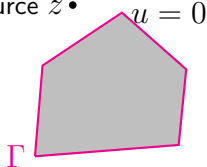
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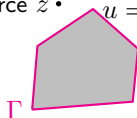
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$$K' \varphi(x) := \int_{\Gamma} \partial_{n(x)} \Phi(x, y) \varphi(y) \, ds(y), \quad S \varphi(x) := \int_{\Gamma} \Phi(x, y) \varphi(y) \, ds(y), \quad x \in \Gamma.$$

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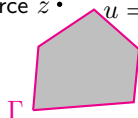
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Point source $z \bullet$

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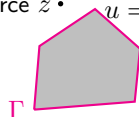
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Integral equation methods: bounded obstacle case

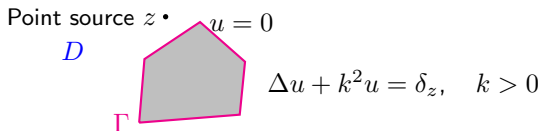
Point source $z \bullet$

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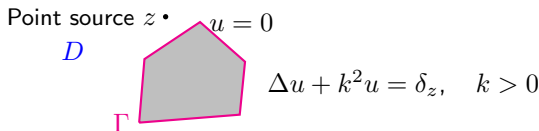
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- **BUT** A is not even compactly perturbed coercive for general Lipschitz Γ , or even for general star-shaped polyhedra in 3D (C-W & Spence 2022a)

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with

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- $\|A^{-1}\| = O(1)$ as $k \rightarrow \infty$ if Γ is star-shaped or smooth and non-trapping (C-W & Monk 2008, Baskin, Spence, Wunsch 2016)
- $\|A\| = O(k^{1/2})$ as $k \rightarrow \infty$ if Γ is star-shaped and 2D, or smooth and non-trapping (C-W et al. 2009, Baskin, Spence, Wunsch 2016)
- A is **uniformly-in- k coercive**, i.e., for all $k_0 > 0$ there exists $\gamma > 0$ such that

$$|(A\varphi, \varphi)| \geq \gamma \|\varphi\|^2, \quad \varphi \in L^2(\Gamma), \quad k \geq k_0,$$

if Γ is **smooth and uniformly convex** (Spence, Kamotski, Smyshlyaev 2016)

- **BUT** A is not even compactly perturbed coercive for general Lipschitz Γ , or even for general star-shaped polyhedra in 3D (C-W & Spence 2022a) **AND** there is no numerical method provably convergent for every polyhedron Γ (**open problem**).

Coercive formulations: bounded obstacle case

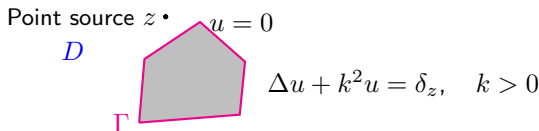
Point source $z \bullet$

D

Γ

$u = 0$

$\Delta u + k^2 u = \delta_z, \quad k > 0$



$$u(x) = u^i(x) - \int_{\Gamma} \Phi(x, y) \partial_n u(y) \, ds(y), \quad x \in D.$$

Taking a linear combination of Dirichlet (γ) and Neumann (∂_n) traces, we obtain the standard 2nd kind integral equation

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and $Z : \Gamma \rightarrow \mathbb{R}^d$ is in $L^{\infty}(\Gamma)$.

Coercive formulations: bounded obstacle case

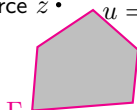
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The diagram shows a gray-shaded polygonal domain D with a magenta boundary Γ . A point source z is indicated by a black dot outside the domain. The boundary Γ is labeled with $u = 0$ at the top vertex.

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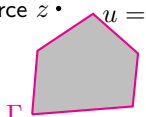
Coercive formulations: bounded obstacle case

Point source $z \bullet$

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Theorem (C-W & Spence 2022b). If Z is continuous and $Z \cdot n \geq c > 0$ on Γ , then $A_Z = A_0 + K$ where A_0 is coercive and K is compact, so that all Galerkin methods for $A_Z \partial_n u = g_Z$ are convergent, provided A_Z is injective.

Coercive formulations: bounded obstacle case

Point source $z \bullet$

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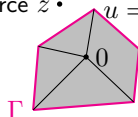
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Sadly injectivity of A_Z not yet clear in general (open problem).

Coercive formulations: bounded obstacle case

Point source $z \bullet$

D



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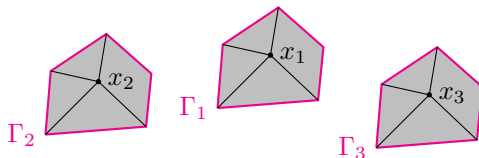
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Theorem (Spence, C-W, Graham, Smyshlyaev 2011). If Γ is **star-shaped** with respect to 0,

$$Z(x) := x, \quad \alpha(x) := k|x| + i(d-1)/2, \quad x \cdot n \geq c > 0,$$

on Γ , then A_Z is **uniformly-in- k coercive** with coercivity constant $\gamma = c/2$, so that all Galerkin methods for $A_Z \partial_n u = g_Z$ are convergent.

Multiple scattering formulation



$$u(x) = u^i(x) - \int_{\Gamma} \Phi(x, y) \partial_n u(y) \, ds(y), \quad x \in D.$$

$$A_Z \partial_n u = g_Z := Z \cdot \gamma \nabla u^i - i k \gamma u^i, \quad \text{where} \quad A_Z := Z \cdot n \left(\frac{1}{2} I + K' \right) + Z \cdot \nabla_{\Gamma} S - i \alpha S.$$

Corollary (Gibbs, C-W, Langdon, Moiola 2021). If each component Γ_j of Γ is star-shaped, and, on Γ_j ,

$$Z(x) := x - x_j, \quad \alpha(x) := k|x - x_j| + i(d-1)/2, \quad (x - x_j) \cdot n \geq c > 0,$$

then $A_Z = A_0 + K$ with A_0 coercive and K compact, **and** A_Z is injective, so that all Galerkin methods for $A_Z \partial_n u = g_Z$ are convergent.

Our typical RSS problem

Suppose $d = 2$ or 3 , $f : \mathbb{R}^{d-1} \rightarrow \mathbb{R}$ is bounded and Lipschitz continuous, precisely

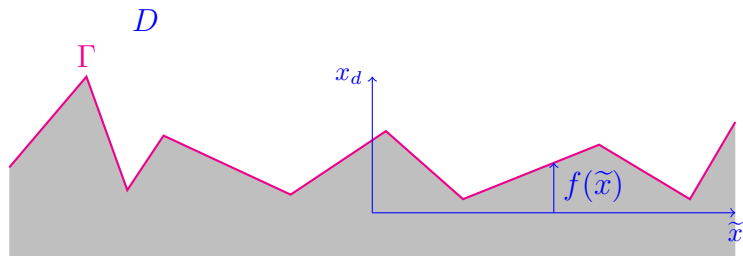
$$0 < f_- \leq f(\tilde{x}) \leq f_+ \quad \text{and} \quad |f(\tilde{x}) - f(\tilde{y})| \leq L|\tilde{x} - \tilde{y}|, \quad \tilde{x}, \tilde{y} \in \mathbb{R}^{d-1}.$$

Our typical RSS problem; the rough surface is Γ

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Let



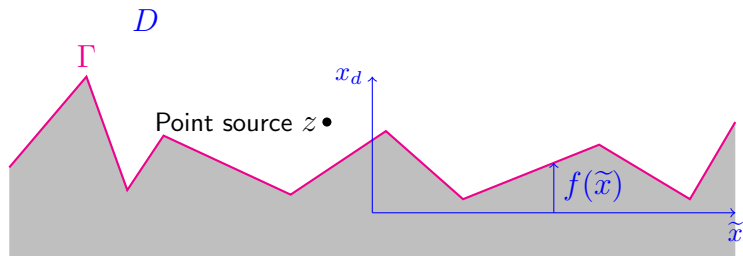
$$D := \{(\tilde{x}, x_d) : x_d > f(\tilde{x}), \tilde{x} \in \mathbb{R}^{d-1}\} \subset \mathbb{R}^d, \quad \Gamma := \partial D = \{(\tilde{x}, f(\tilde{x})) : \tilde{x} \in \mathbb{R}^{d-1}\}.$$

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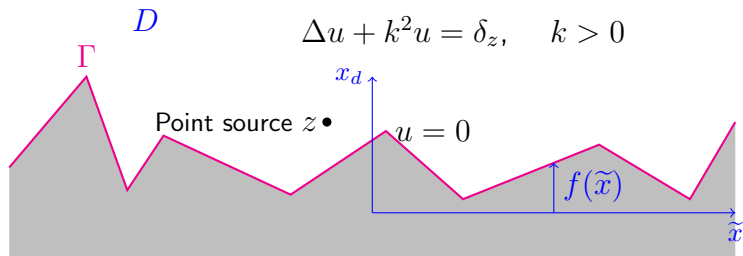
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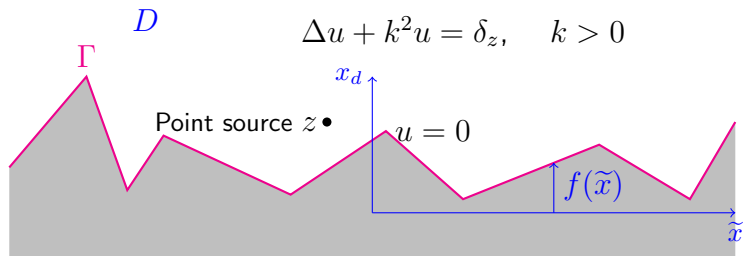
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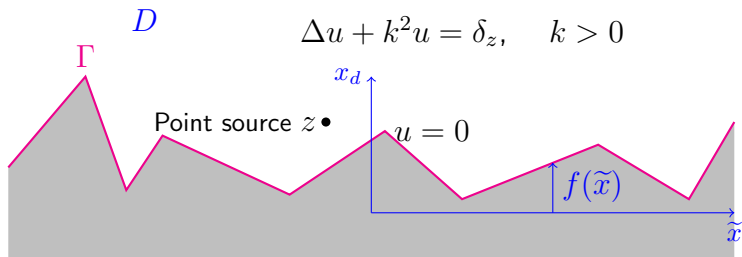
Key feature: Γ **unbounded** (in the horizontal directions).

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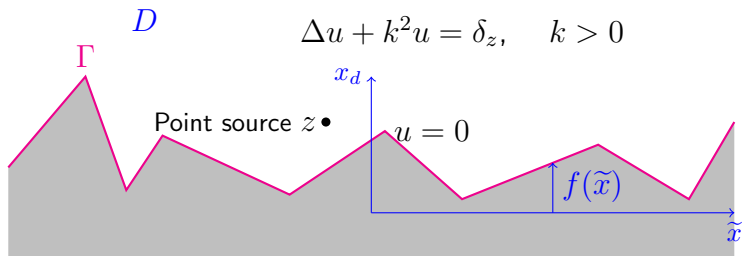
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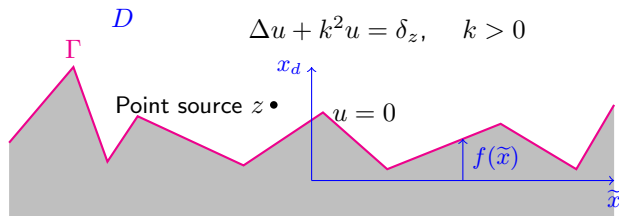


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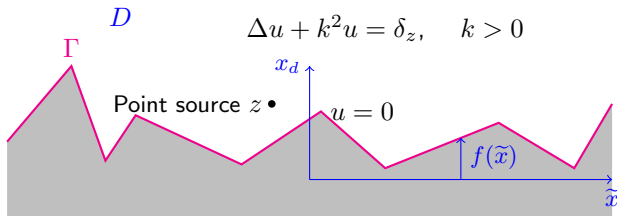
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Applications in outdoor noise or radar propagation over ground and sea surfaces, and in optics: all nominally flat surfaces are rough at some scale!

Integral equation methods: rough surface scattering



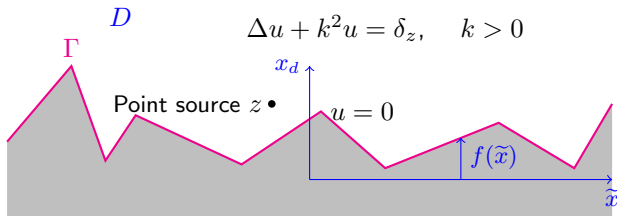
Integral equation methods: rough surface scattering



First idea: just use the **bounded obstacle formulation**, i.e.

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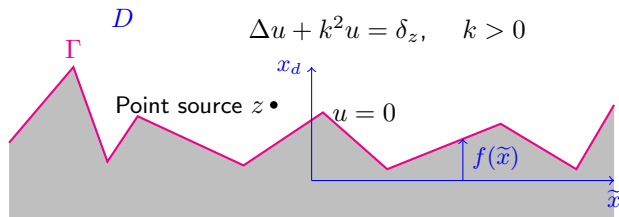
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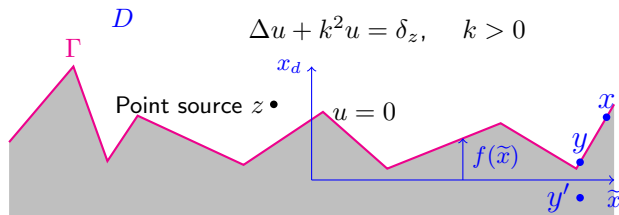
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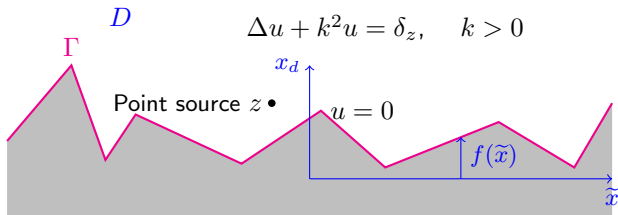
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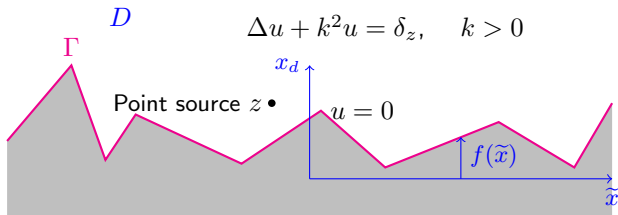
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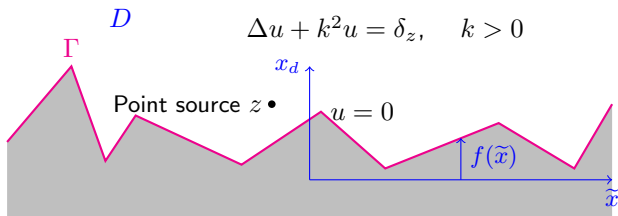
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Theorem (C-W, Heinemeyer, Potthast 2006a,b). A is bounded and invertible on $L^2(\Gamma)$, indeed, where L is the Lipschitz constant of f ,

$$\|A^{-1}\| \leq 12(1 + L)^2.$$



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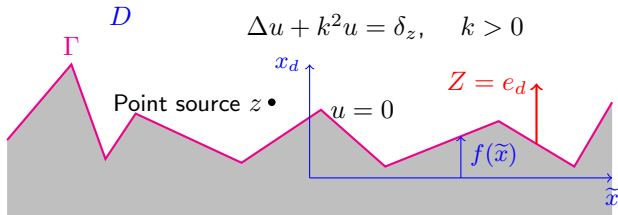
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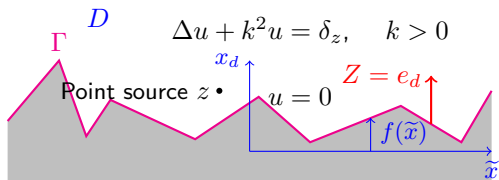
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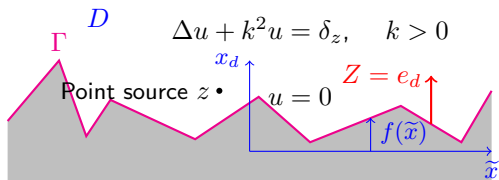
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Theorem. With $Z = e_d$, A_Z is bounded and **uniformly-in- k coercive** on $L^2(\Gamma)$, with coercivity constant

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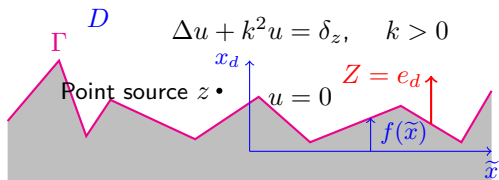
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- The convergence theory for Galerkin BEM and GMRES recalled earlier

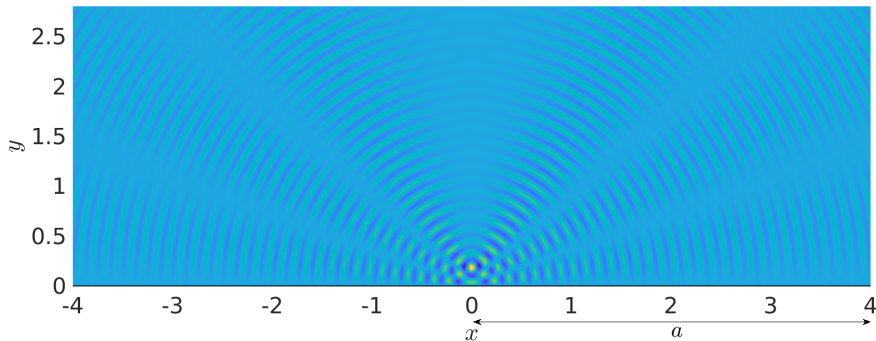
Numerical results: flat Γ : $f(\tilde{x}) = f_- = 0.25$

2D numerical results when Γ is flat, applying h -BEM with P1 elements and uniform mesh on part of surface of length $2a$, with

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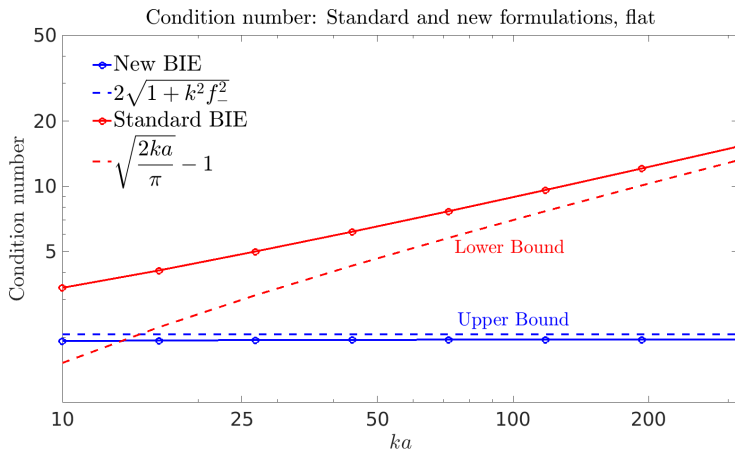


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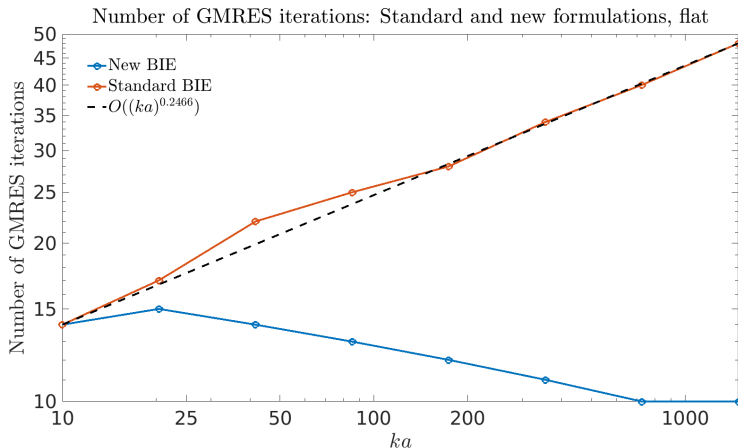


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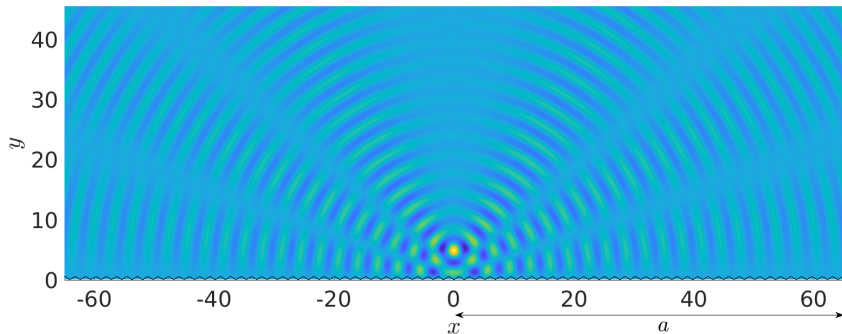
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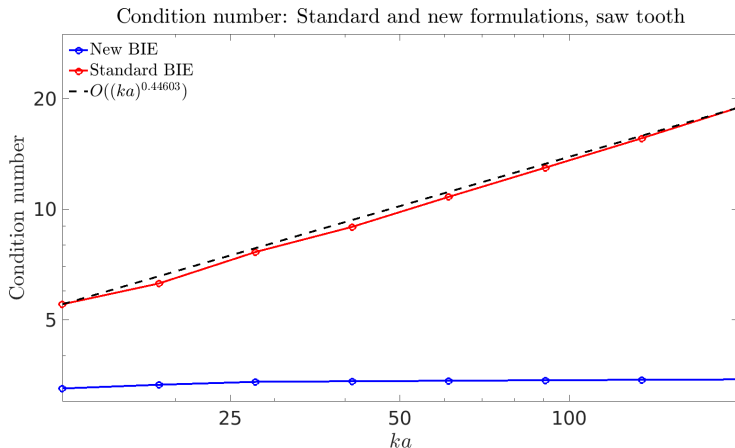


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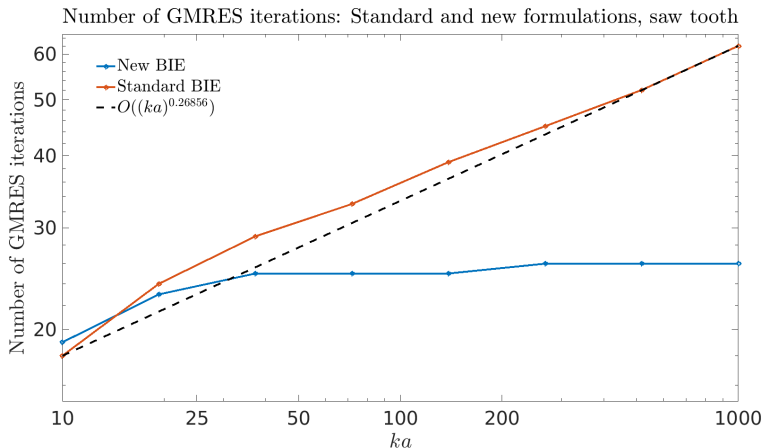


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- Recalled recent novel 2nd kind integral equations for bounded obstacles, with A replaced by an operator $A_Z := Z \cdot n(\frac{1}{2}I + K') + Z \cdot \nabla_\Gamma S - ikS$ which is coercive + compact
- Proposed a new 2nd kind integral equation of this type for our RSS problem with $Z = e_d$, the constant vertical unit vector, for which A_Z is **bounded and uniformly-in- k coercive**, leading to proof of **convergence of combined surface truncation/Galerkin BEM**, and **convergence of GMRES** in a number of iterations independent of the element diameter h and the truncated surface diameter a .

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